

Hence, using Lemma 4.9 again yields

$$\begin{aligned} |u - u_N|_1 + k\|u - u_N\| &\leq c(|e_N|_1 + k\|e_N\| + |\tilde{e}_N|_1 + k\|\tilde{e}_N\|) \\ &\leq c(1 + k^2N^{-1} + kN^{-1/2})\sqrt{\frac{(N-m+1)!}{N!}}(N+m)^{(1-m)/2}\|(r-r^2)^{(m-1)/2}\partial_r^m u\|. \end{aligned}$$

This ends the proof. \square

Problems

4.1. Show that under the assumption (4.3), the bilinear form $\mathcal{B}(\cdot, \cdot)$ defined by (4.9) is continuous and coercive in $H_\diamond^1(I) \times H_\diamond^1(I)$.

4.2. Let $\{h_j\}_{j=0}^N$ be the Lagrange basis polynomials relative to the Jacobi-Gauss-Radau points $\{x_j\}_{j=0}^N$ with $x_0 = -1$ (see Theorem 3.26). Let $\tilde{D} = (d_{kj} := h'_j(x_k))_{1 \leq k, j \leq N}$ be the differentiation matrix corresponding to the interior collocation point (see (3.163)). Write down the matrix form of the Jacobi-Gauss-Radau collocation method for

$$u'(x) = f(x), \quad x \in (-1, 1); \quad u(-1) = c_-,$$

where $f \in C[-1, 1]$ and c_- is a given value. Use the uniqueness of the approximate solution to show that the matrix \tilde{D} is nonsingular.

4.3. Prove Lemma 4.8.

4.4. Consider the Burgers' equation:

$$\frac{\partial u}{\partial t} = \varepsilon \frac{\partial^2 u}{\partial x^2} - u \frac{\partial u}{\partial x}, \quad \varepsilon > 0. \quad (4.120)$$

(i) Verify that it has the soliton solution

$$u(x, t) = \kappa \left[1 - \tanh \left(\frac{\kappa(x - \kappa t - x_c)}{2\varepsilon} \right) \right], \quad (4.121)$$

where the parameter $\kappa > 0$ and the center $x_c \in \mathbb{R}$.

(ii) Take $\varepsilon = 0.1$, $\kappa = 0.5$, $x_c = -3$, $x \in [-5, 5]$, and impose the initial value $u(x, 0)$ and the boundary conditions $u(\pm 5, t)$ by using the exact solution. Use the Crank-Nicolson leap-frog scheme to in time (see (1.2)–(1.3)), and the Chebyshev collocation method in space to solve the equation. Output the discrete maximum errors for $\tau = 10^{-k}$ (time step size) with $k = 2, 3, 4$ and $N = 32, 64, 128$ at $t = 12$. Refer to Table 1 in Wu et al. (2003) for the behavior of the errors (obtained by other means).

(iii) Replace the Chebyshev-collocation method in (ii) by the Chebyshev-Galerkin method. Do the same test and compare two methods. Refer to Sect. 3.4.3 for the

Chebyshev differentiation process using FFT and to Trefethen (2000) for a handy MATLAB code for this process.

(iv) Consider the Burgers' equation (4.120) in $(-1, 1)$ with the given data

$$u(\pm 1, t) = 0, \quad u(x, 0) = -\sin(\pi x), \quad x \in [-1, 1]. \quad (4.122)$$

Solve this problem by the methods in (ii) and (iii) by taking $\varepsilon = 0.02$, $\tau = 10^{-4}$ and $N = 128$ and plot the numerical solution at $t = 1$. Refer to Shen and Wang (2007b) for some profiles of the numerical solution (obtained by other means).

4.5. Consider the Fisher equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + u(1 - u). \quad (4.123)$$

(i) Verify that it has the traveling solution

$$u(x, t) = \left[1 + \exp\left(\frac{x}{\sqrt{6}} - \frac{5}{6}t\right) \right]^{-2}. \quad (4.124)$$

(ii) Since $u(x, t) \rightarrow 0$ (resp. 1) as $x \rightarrow +\infty$ (resp. $-\infty$), we can approximate (4.123) in $(-L, L)$, where L is large enough so that the wave front does not reach the boundary $x = L$, by imposing the boundary conditions

$$u(-L, t) = 1, \quad u(L, t) = 0,$$

and taking the initial value as $u(x, 0)$. Use the second-order splitting scheme (D.30) with $Au = \partial_x^2 u$ and $Bu = u(1 - u)$ in time, and the Legendre-Galerkin method in space to solve this problem with $\tau = 10^{-3}$, $N = 128$, $L = 100$ up to $t = 6$. Output the discrete maximum errors between the exact and approximate solutions at $t = 1, 2, \dots, 6$. An advantage of the splitting scheme is that the subproblem (a Bernoulli's equation for t):

$$\frac{\partial u}{\partial t} = u(1 - u)$$

can be solved exactly, so it suffices to solve a linear equation in each step. Refer to Wang and Shen (2005) for this numerical study by a mapping technique.